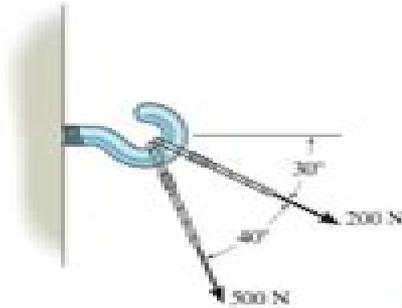
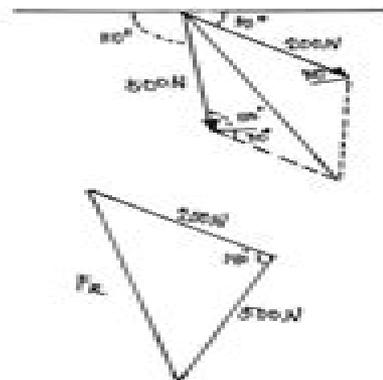


F2-2. Two forces act on the hook. Determine the magnitude of the resultant force.



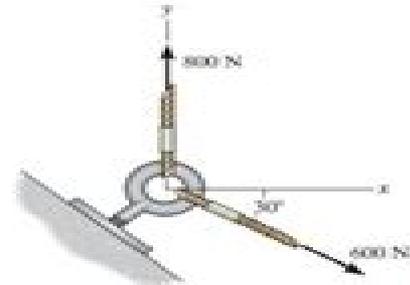
Prob. F2-2



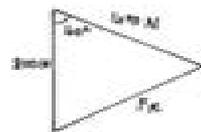
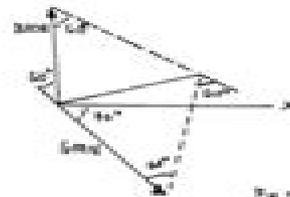
$$F_R = \sqrt{500^2 + 200^2 - (2)(500)(200)(\cos 40^\circ)}$$

$$F_R = 665.7 \text{ N}$$

F2-3. Determine the magnitude of the resultant force and its direction measured counterclockwise from the positive x axis.



Prob. F2-3



$$F_R = \sqrt{500^2 + 300^2 - (2)(500)(300)(\cos 40^\circ)}$$

$$F_R = 721.1 \text{ N}$$

$$\frac{500}{721.1} = \frac{300 \cdot \sin 40^\circ}{721.1 \sin \theta}$$

$$\theta = 46.1^\circ$$

Angle between x-axis

$$\phi = 90^\circ - 46.1^\circ = 43.9^\circ$$

Engineering Mechanics Problems And Solutions

S Rajasekaran



Engineering Mechanics Problems And Solutions:

Problems and Solutions in Engineering Mechanics S. S. Bhavikatti, A. Vittal Hegde, 2009-05-30 Each chapter begins with a quick discussion of the basic concepts and principles It then provides several well developed solved examples which illustrate the various dimensions of the concept under discussion A set of practice problems is also included to encourage the student to test his mastery over the subject The book would serve as an excellent text for both Degree and Diploma students of all engineering disciplines AMIE candidates would also find it most useful *Engineering Mechanics* Thomas Alexander Hunter, 1961 **Solving Practical Engineering Mechanics Problems** National Geographic Society, Sayavur I. Bakhtiyarov, 2018-04-10 Intro Acknowledgments Topic K 1 1 1 Determining Velocity and Acceleration of Particles by Given Equations of Motion 1 2 Sample Problem 1 3 Solution Topic K 2 2 1 Determination of Velocities and Accelerations of Particles of Rigid Bodies Being in Translational and Rotational Motions 2 2 Sample Problem 2 3 Solution Topic K 3 3 1 Determination of Velocities of Rigid Body in Plane Motion 3 2 Sample Problem 3 3 Solution Topic K 4 4 1 Determination of Velocities and Accelerations of Points of Rigid Body in Plane Motion 4 2 Sample Problem 4 3 Solution Topic K 5 5 1 Determination of Absolute Velocity and Absolute Acceleration of Particle 5 2 Sample Problem 5 3 Solution Topic K 6 6 1 Determination of Absolute Velocity and Absolute Acceleration of Particle in Rotational Transfer Motion 6 2 Sample Problem 6 3 Solution Author Biography Blank Page **Problems & Solutions in Engineering Mechanics** Exp. Teachers, 2004-02-01

Engineering Mechanics D. P. Sharma, Sharma D. P., 2010 This book is tailor made as per the syllabus of Engineering Mechanics offered in the first year of undergraduate students of Engineering The book covers both Statics and Dynamics and provides the students with a clear and thorough presentation of the theory as well as the applications The diagrams and problems in the book familiarize students with actual situations encountered in engineering Engineering Mechanics A. Bedford, Wallace L. Fowler, 2008 This textbook is designed for introductory statics courses found in mechanical engineering civil engineering aeronautical engineering and engineering mechanics departments It better enables students to learn challenging material through effective efficient examples and explanations *Engineering Mechanics* Irving Herman Shames, 1960 Solutions to Problems in Statics in Engineering Mechanics: Statics Stephen Timoshenko, Donovan Harold Young, 1956 *Solving Practical Engineering Mechanics Problems* Sayavur I. Bakhtiyarov, 2018-05-04 Engineering Mechanics is one of the fundamental branches of science that is important in the education of professional engineers of any major Most of the basic engineering courses such as mechanics of materials fluid and gas mechanics machine design mechatronics acoustics vibrations etc are based on an Engineering Mechanics course In order to absorb the materials of Engineering Mechanics it is not enough to consume just theoretical laws and theorems a student also must develop an ability to solve practical problems Therefore it is necessary to solve many problems independently This book is a part of a four book series designed to supplement the Engineering Mechanics courses in the principles required to solve practical engineering

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Solutions Manual for Engineering Mechanics R. C. Hibbeler,1974

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Engineering Mechanics, 1896 *Engineering Mechanics 2* Dietmar Gross, Werner Hauger, Jörg Schröder, Wolfgang A. Wall, Javier Bonet, 2018-03-12 Now in its second English edition Mechanics of Materials is the second volume of a three volume textbook series on Engineering Mechanics It was written with the intention of presenting to engineering students the basic concepts and principles of mechanics in as simple a form as the subject allows A second objective of this book is to guide the students in their efforts to solve problems in mechanics in a systematic manner The simple approach to the theory of mechanics allows for the different educational backgrounds of the students Another aim of this book is to provide engineering students as well as practising engineers with a basis to help them bridge the gaps between undergraduate studies advanced courses on mechanics and practical engineering problems The book contains numerous examples and their solutions Emphasis is placed upon student participation in solving the problems The new edition is fully revised and supplemented by additional examples The contents of the book correspond to the topics normally covered in courses on basic engineering mechanics at universities and colleges Volume 1 deals with Statics and Volume 3 treats Particle Dynamics and Rigid Body Dynamics Separate books with exercises and well elaborated solutions are available

Dynamics - Formulas and Problems Dietmar Gross, Wolfgang Ehlers, Peter Wriggers, Jörg Schröder, Ralf Müller, 2016-10-05 This book contains the most important formulas and more than 190 completely solved problems from Kinetics and Hydrodynamics It provides engineering students material to improve their skills and helps to gain experience in solving engineering problems Particular emphasis is placed on finding the solution path and formulating the basic equations Topics include Kinematics of a Point Kinetics of a Point Mass Dynamics of a System of Point Masses Kinematics of Rigid Bodies Kinetics of Rigid Bodies Impact Vibrations Non Inertial Reference Frames Hydrodynamics

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